

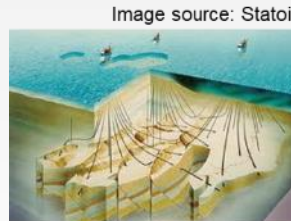


Revealing governing mechanisms in hydraulic stimulation of geothermal reservoirs by mathematical and numerical modelling

Inga Berre



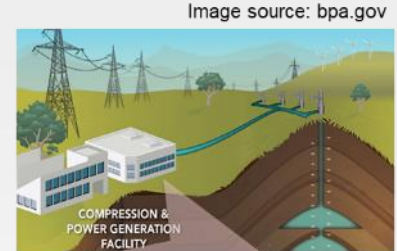
University of Bergen Porous media group research activities – an illustration of the energy transition in geosciences



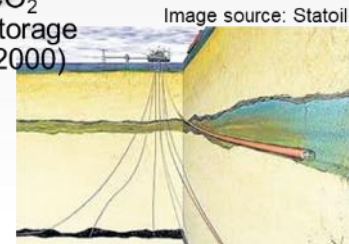
Petroleum
(1985)



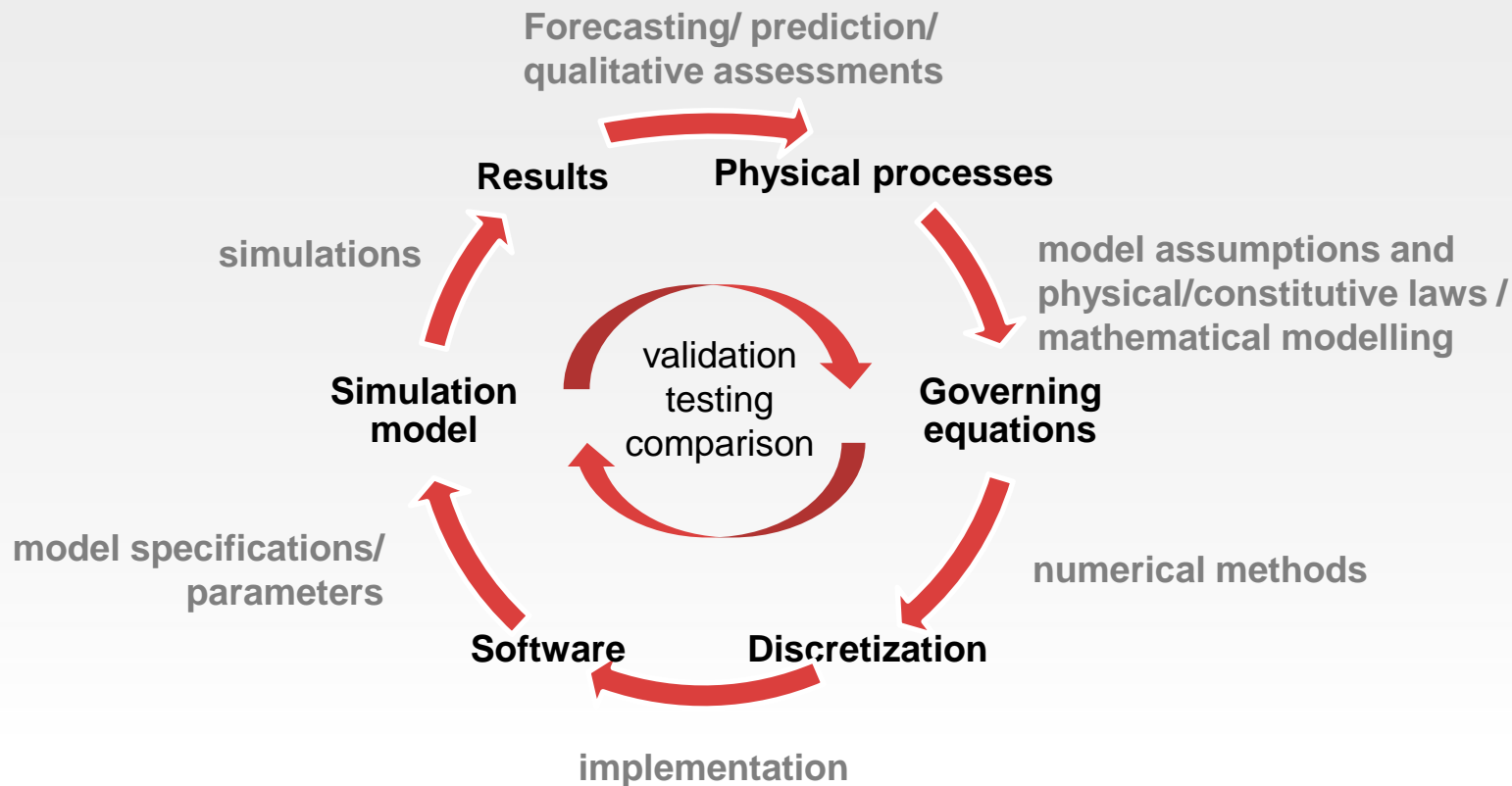
Geothermal
Energy
(2008)



Energy
Storage
(2014)



Computational geoscience





Geothermal systems



Utilization of deep geothermal sources requires sufficient

- heat
- fluid
- permeability

Resource types

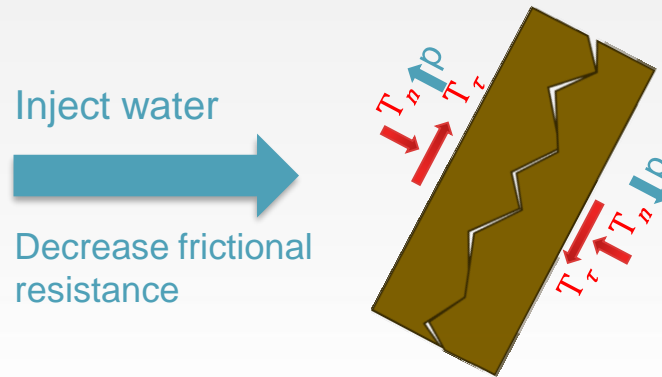
- conventional hydrothermal
- **enhanced geothermal systems**
- superheated / supercritical



Enhanced geothermal systems

- Hydraulic stimulation by shear dilation

- Natural fractures already exist
- Large difference between maximum and minimum horizontal stress
- Prior stable situation due to friction between fracture surfaces
- Injection of fluid at elevated pressures results in slip and dilation

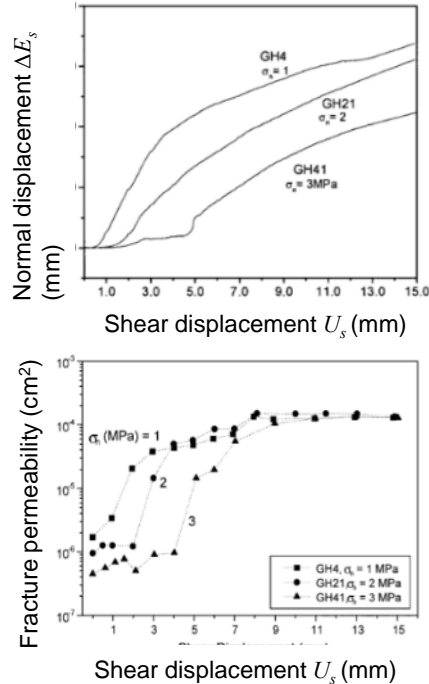


The relative displacement of the fracture's surfaces with slip results in dilation of the fracture

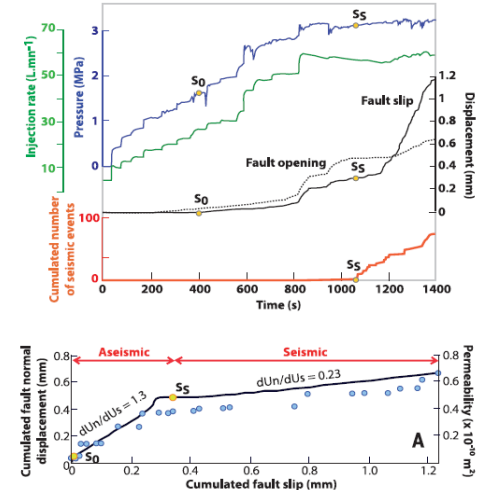
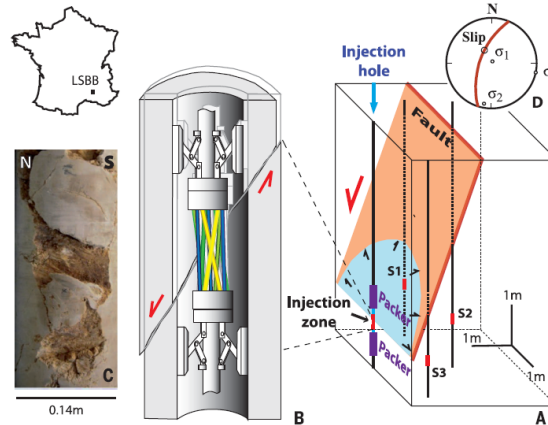
Hydraulic stimulation measurements in lab and field



Lab-measurements of fracture permeability under shear and normal load



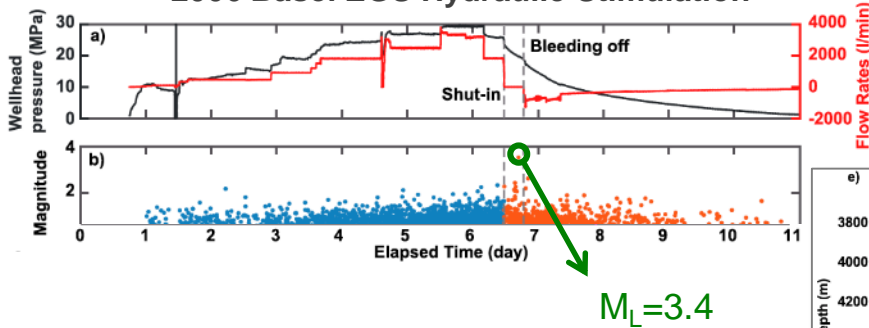
Measurement of fault slip and permeability enhancement induced by fluid injection into a natural fault



Induced Seismicity

- In hydraulic stimulation, seismicity is deliberately induced
- Generally $M_L < 3.0$ (micro earthquake)
- Larger earthquakes must be avoided

2006 Basel EGS Hydraulic Stimulation



$M_L = 3.4$

Science

REPORTS

Cite as: K.-H. Kim et al., *Science* 10.1126/science.aan6081 (2018).

Assessing whether the 2017 M_w 5.4 Pohang earthquake in South Korea was an induced event

Kwang-Hee Kim,^{1,*} Jin-Han Ree,^{2*} YoungHee Kim,³ Sungshil Kim,³ Su Young Kang,⁴ Woosook Seo⁵

¹Department of Geological Science, Pusan National University, 2841, Republic of Korea; ²School of Earth and Environmental Science, Seoul National University, 151-747, Seoul, Republic of Korea; ³Department of Earth Science, Seoul National University, 151-747, Seoul, Republic of Korea; ⁴Department of Earth Science, Seoul National University, 151-747, Seoul, Republic of Korea; ⁵Department of Earth Science, Seoul National University, 151-747, Seoul, Republic of Korea

The M_w 5.4 Pohang earthquake observation began in 1905, on geophysical data suggest that system (EGS) site, which was magnitude of the mainshock

The injection of fluid into reservoir oil and gas recovery, enhances geothermal energy production, but the chance of inducing earthquakes (e.g., 2, 5). The magnitude of an induced event is controlled by the injection rate and the magnitude of the mainshock. This may be fault suitably oriented for slip and is also located adjacent to one or more faults (6, 7). The earthquake magnitude is controlled by the injection (8). The magnitude of induced seismicity at enhanced geothermal systems (EGS) sites is relatively small (9). The magnitude of the mainshock (10) reported was a M_w 3.4 at a depth of 7 km, possibly induced by the injection of fluid. The earthquake occurred on 15 November 2017, was the most damaging in South Korea since 1978 when scientific investigation began. The earthquake injured 10 people and caused property damage was US\$5 million. Evidence that suggests the Pohang induced event at any EGS site is not clear. The earthquake magnitude indicates that injected fluid is not the cause of the earthquake, but rather the earthquake is a natural event, at least under the right set of conditions. The Korean Peninsula lies with

Science

REPORTS

Cite as: F. Grigoli et al., *Science* 10.1126/science.aan2010 (2018).

The November 2017 M_w 5.5 Pohang earthquake: A possible case of induced seismicity in South Korea

F. Grigoli,^{1,*} S. Cesca,² A. P. Rinaldi,³ A. Manconi,⁴ J. A. López-Comino,⁵ J. F. Clinton,⁶ R. Westaway,⁷ C. Cauzzi,⁸ T. Dahm,⁹ S. Wiemer¹⁰

¹ETH Zurich, Swiss Seismological Service, Zurich, Switzerland; ²GFZ Potsdam, Section 2.1, Physics of Earthquakes and Volcanoes, Potsdam, Germany; ³ETH Zurich, Department of Earth Sciences, Engineering Geology, Zurich, Switzerland; ⁴University of Glasgow, School of Engineering, Glasgow, UK; ⁵University of Potsdam, Institute of Earth and Environmental Sciences, Potsdam, Germany; ⁶University of Cambridge, School of Earth and Atmospheric Sciences, Cambridge, UK; ⁷University of Cambridge, School of Earth and Atmospheric Sciences, Cambridge, UK; ⁸University of Cambridge, School of Earth and Atmospheric Sciences, Cambridge, UK; ⁹University of Cambridge, School of Earth and Atmospheric Sciences, Cambridge, UK; ¹⁰University of Cambridge, School of Earth and Atmospheric Sciences, Cambridge, UK

The M_w 5.5 earthquake that struck South Korea in November 2017 was one of the largest and most damaging events in this country over the last century. Its proximity to an Enhanced Geothermal Systems site, where high pressure hydraulic injection had been performed during the previous two years, raises the possibility that this earthquake was anthropogenic. We have combined seismological and geodetic analyses to characterize the mainshock and its largest aftershocks, constrain the geometry of this seismic sequence and shed light on its causal factors. According to our analysis it seems plausible that the occurrence of this earthquake was influenced by these industrial activities. Finally we found that the earthquake transferred static stress to larger nearby faults, potentially increasing the seismic hazard in the area.

Deep geothermal resources can give a valuable contribution to the production of renewable energy. Through Enhanced Geothermal Systems (EGS), geothermal energy production is no longer confined to volcanic or hydrothermal regions. EGS technologies, unlike the conventional geothermal systems, exploit geothermal resources through hydraulic stimulation, which involves injecting pumping high-pressure cold water to increase the permeability of the target formation at a few kilometers depth, by creating new fractures or enhancing existing ones. While the potential for deep geothermal energy

causal connection between the EGS activity and the most recent large earthquake. The Korean Peninsula is generally considered stable with low to moderate intraplate seismic activity, but historical seismicity of this region indicates large secular variations in earthquake rate and energy release (4, 5). The relatively low activity since 1904 was preceded by much higher activity between the 15th to 18th centuries, with a peak of 1000 reported historical earthquakes between 1500 and 1800 AD (5). The largest events reached magnitude >7 (4, 5). The historic earthquakes were likely associated with the major fault systems of the area, such as the Yangsan Fault, and highlight that these structures are active (4, 5). In principle, given the historically varying rates of seismicity and prevalence of faults in this region, the increase represented by the 2016 Gyeongju and 2017 Pohang earthquakes is not completely inconsistent with the historically varying rates of seismicity. This leaves open the possibility that the occurrence of earthquakes close to the EGS site is a coincidence.

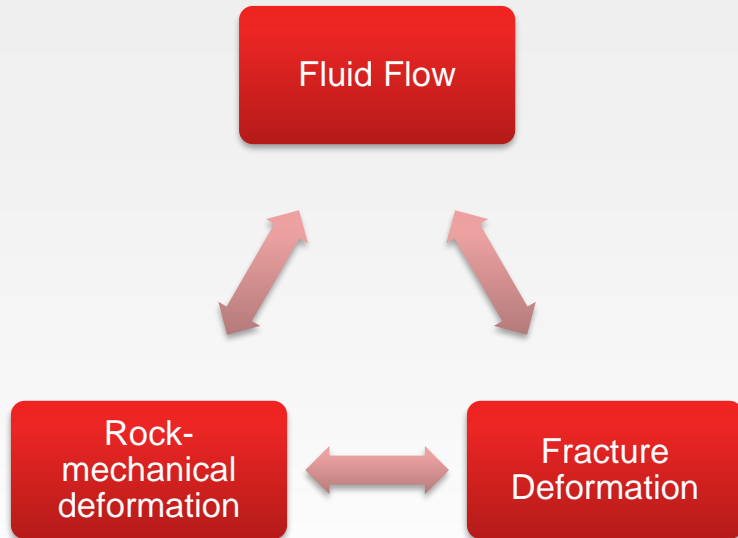
We applied full-waveform seismological methods to regional and teleseismic data (Fig. 1A) (6) as we do not have access to open data from a local seismic network (with the exception of two accelerometers deployed in the epicentral area). We analyzed 15 days of continuous waveform data covering November 15–30. We detected and relocated 46 events, most with magnitude $M < 2$. The trend of these 46 epicenters indicates a WSW–ENE strike of the fault that ruptured in the mainshock (Fig. 2A). We determined 3–7 km hypocentral depths for most of these events (Fig. 2A). This depth is shallower than typical seismicity in the area which is of about

www.sciencemag.org (Page numbers not final at time of first release) 1

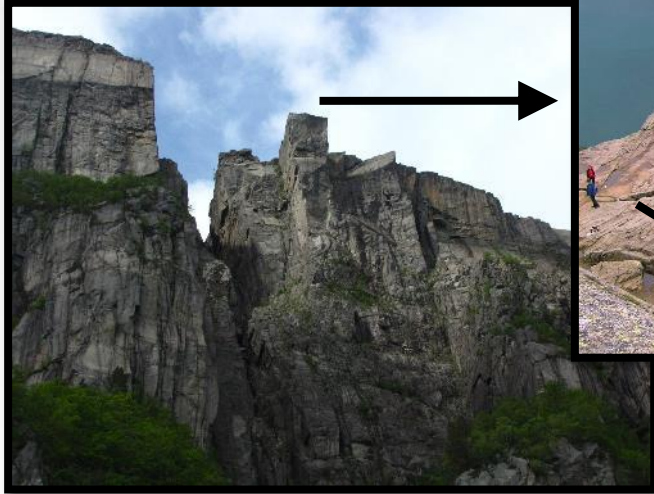


Mathematical modeling

– coupled processes



Structure



Credits: A. Gohr

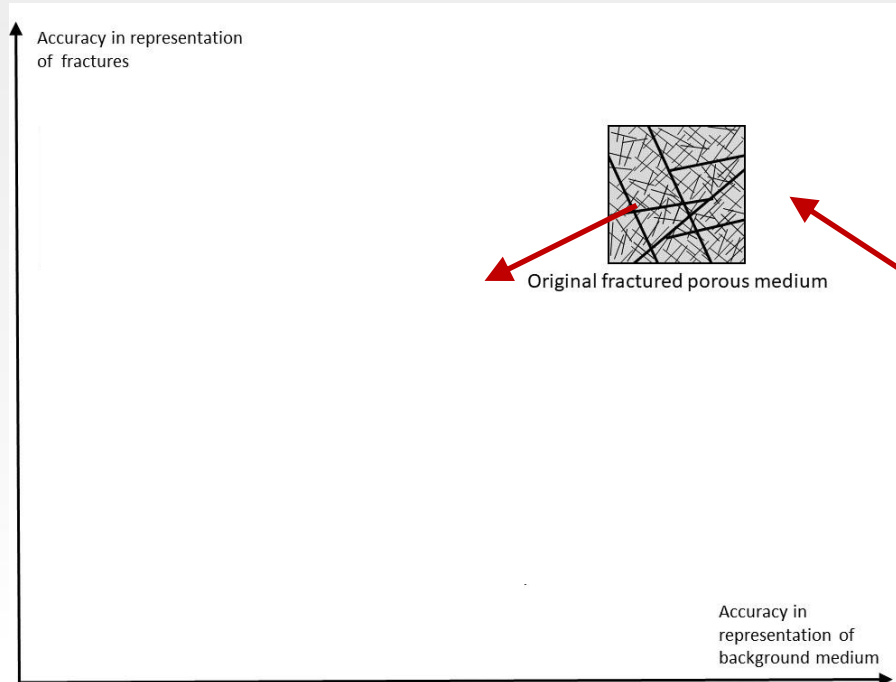


Credits: Stavanger Aftenblad

different scales – complex structure



Mathematical modeling - representation of fractures



Modeling - Flow

Assumptions: single-phase, weakly compressible fluid
Conservation of Mass

$$\phi c \frac{\partial p}{\partial t} + \nabla \cdot \mathbf{w} = q,$$

$$\phi_f c \frac{\partial p}{\partial t} + \nabla^{\parallel} \cdot \mathbf{w}_f^{\parallel} = q_f + \frac{1}{d_n} (w_{\Gamma^+}^{\perp} + w_{\Gamma^-}^{\perp}),$$

$$\mathbf{x} \in \Omega_m \in \mathbb{R}^3$$

$$\mathbf{x} \in \Omega_f \in \mathbb{R}^2$$

Darcy velocity

$$\mathbf{w} = -\frac{K}{\mu} \nabla p,$$

$$\mathbf{x} \in \Omega_m \in \mathbb{R}^3$$

$$\mathbf{w}_f^{\parallel} = -\frac{K_f^{\parallel}}{\mu} \nabla^{\parallel} p,$$

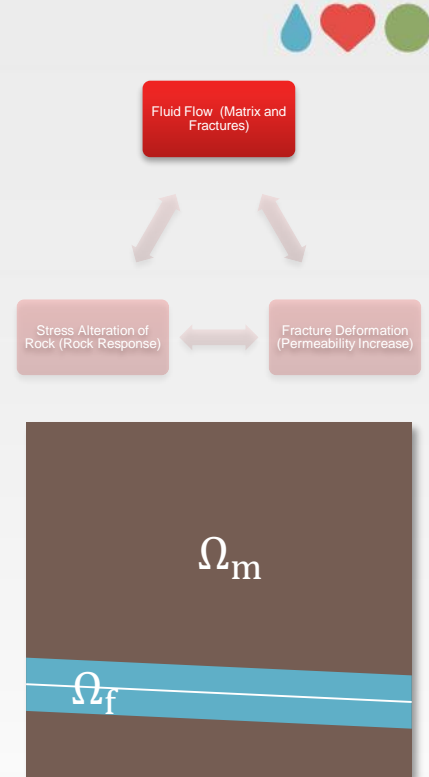
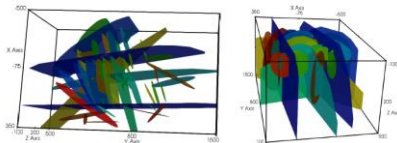
$$\mathbf{x} \in \Omega_f \in \mathbb{R}^2$$

Cubic law

$$K_f = \frac{e^2}{12}.$$

Numerical approach

- Fractures are treated as co-dimension one
- Cell-centered finite-volume method (two-point flux approximation).



Fracture deformation

Static/dynamic friction model
Mohr–Coloumb criterion

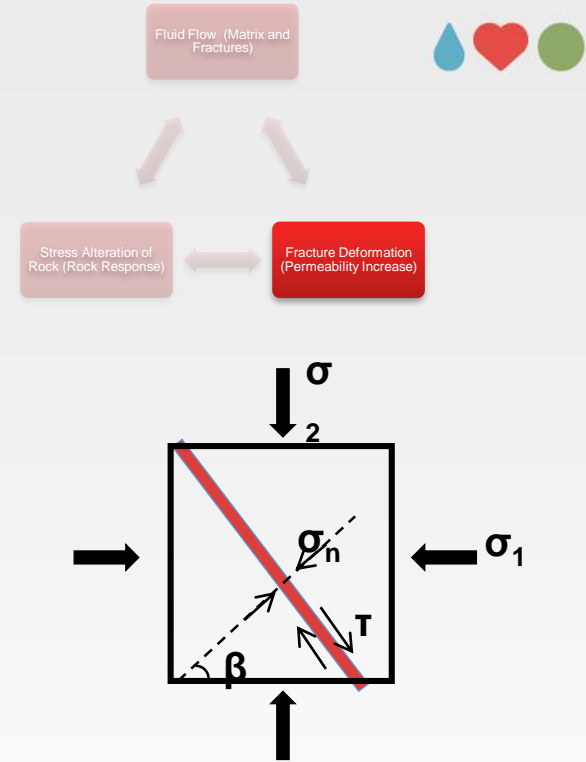
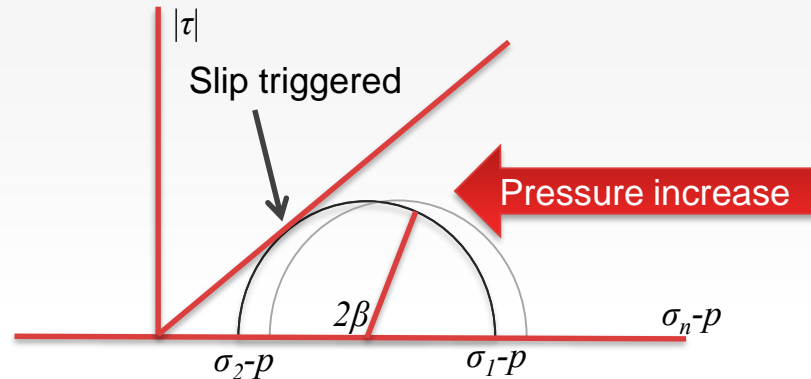
$$|\boldsymbol{\tau}| < \mu_s(\sigma_n - p) \rightarrow [d_s] = 0$$

$$x \in \Gamma_f \setminus \Gamma_s$$

$$|\boldsymbol{\tau}| = \mu_d(\sigma_n - p) \rightarrow [d_s] = \alpha \boldsymbol{\tau}, \alpha > 0$$

$$x \in \Gamma_s$$

$$\mu_d < \mu_s$$



Fracture deformation

Dilation:

$$d_n = E_0 - E_e + E_s$$

$$E_s = d_s \tan \varphi_{\text{dil}},$$

Fracture displacement:

$$\mathbf{u}_- - \mathbf{u}_+ = d_n \mathbf{n}_+ + d_s \boldsymbol{\zeta}_+$$

Approximated shear displacement (excess shear stress approximation):

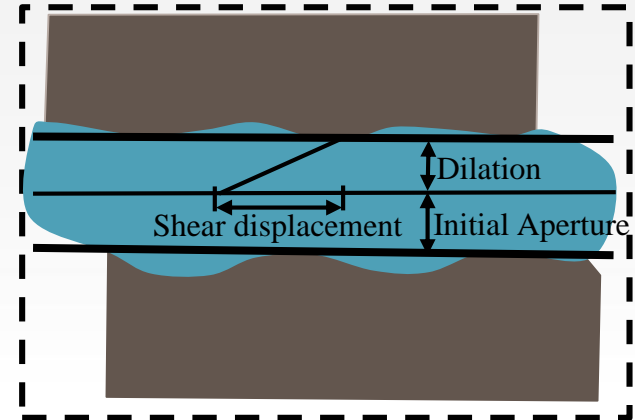
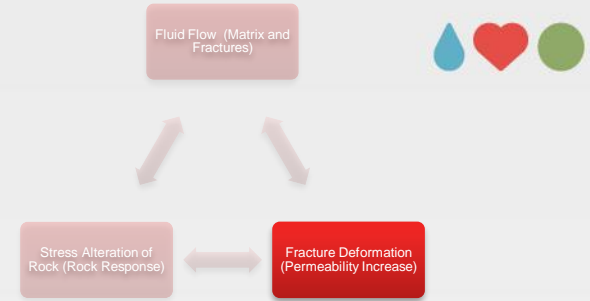
$$[d_s] = \frac{|\boldsymbol{\tau}| - \mu_d(\sigma_n - p)}{K_s}$$

Reversible normal deformation (Barton-Bandis):

$$E_e = \frac{-(\sigma_n - p)}{K_n + \frac{\sigma_n - p}{E_{\text{max}}}}$$

Hydraulic aperture

$$e = \frac{d_n^2}{JRC^{2.5}}$$



Stress response of matrix due to fracture deformation

Assumptions: quasi-static problem, isotropic medium

Conservation of Momentum:

$$\nabla \cdot \boldsymbol{\sigma} = \mathbf{0},$$

Hooke's law

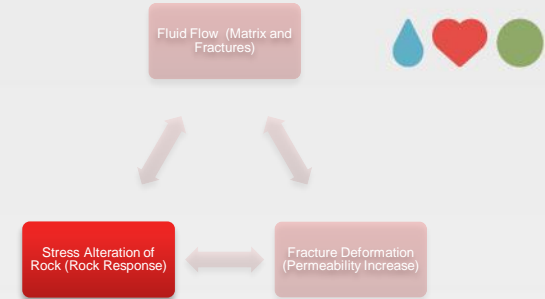
$$\boldsymbol{\sigma} = 2G\boldsymbol{\varepsilon} + \lambda \operatorname{tr}(\boldsymbol{\varepsilon})\mathbf{I},$$

$$\boldsymbol{\varepsilon} = \frac{(\nabla \mathbf{u} + (\nabla \mathbf{u})^T)}{2},$$

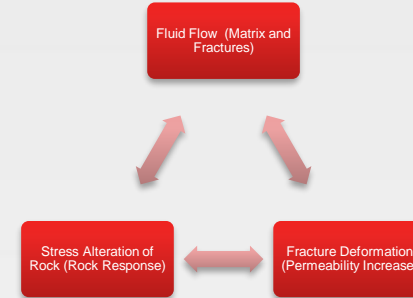
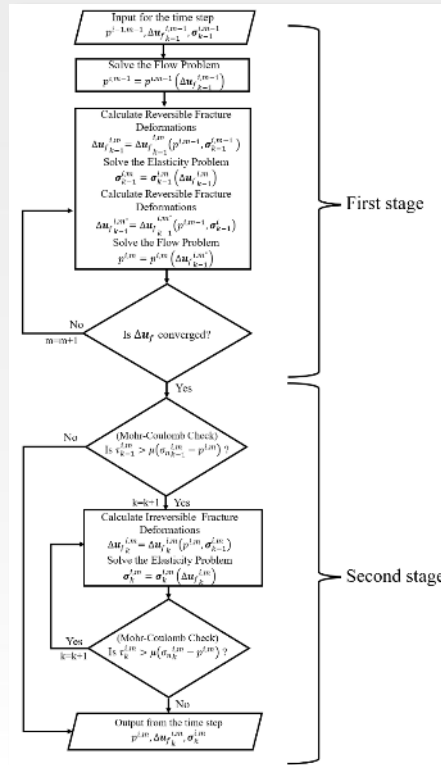
Fracture deformations as conditions on internal boundaries

Numerical Approach

Cell-centered finite-volume method (MPSA) for fractured media



Hydro-mechanical coupling

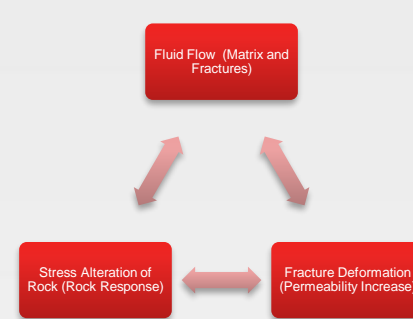
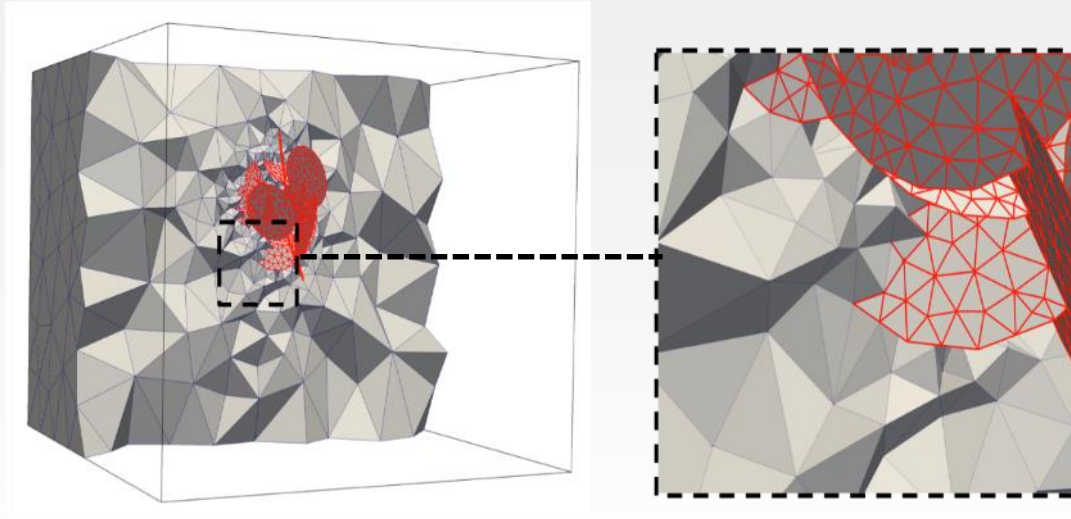


First stage: balance between fluid flow, reversible fracture deformation, stress response of the matrix

Second stage: capturing of the irreversible fracture deformation and stress response of the matrix

Hydraulic stimulation results

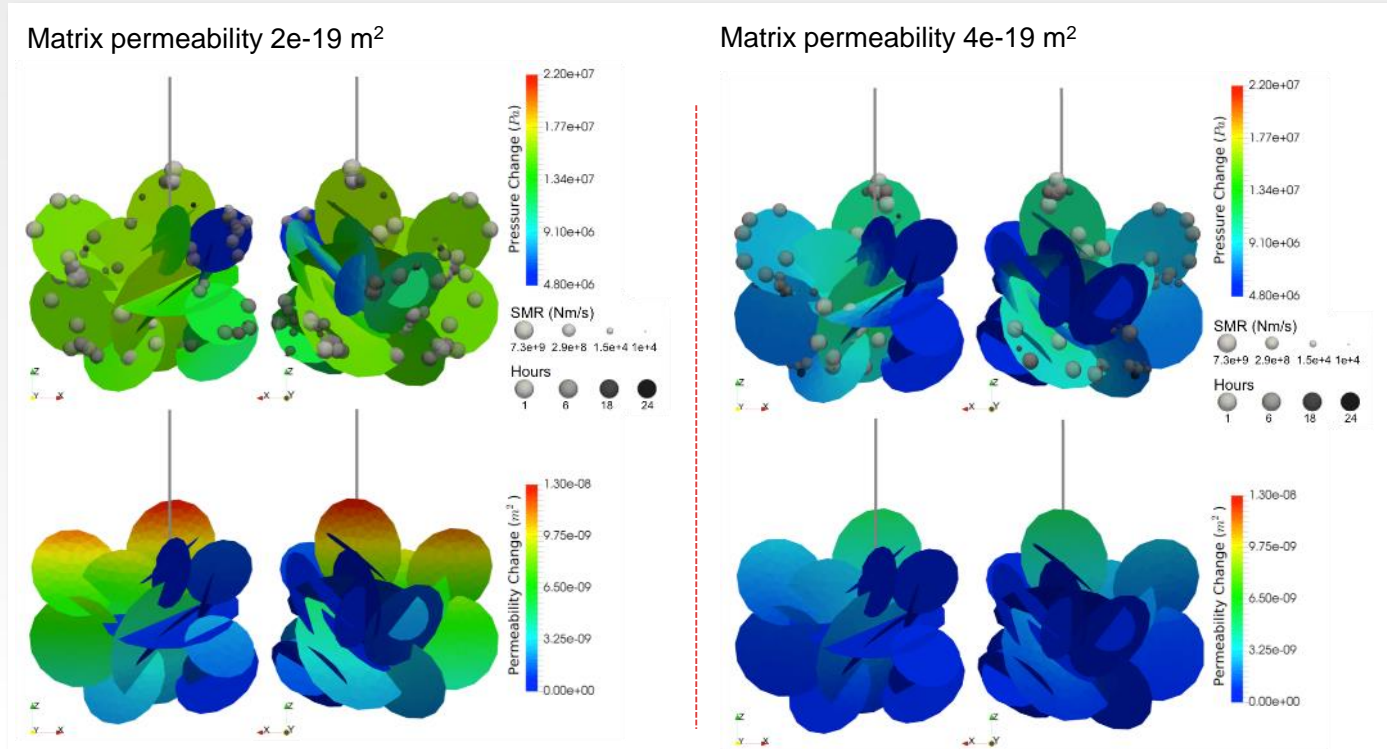
Fracture network with 20 fractures
in a porous medium domain.



Results: effect of background permeability



Permeability change and induced seismicity after 1 day of stimulation.



Postinjection seismicity due to reversible normal deformation of fractures



With normal closure



Without normal closure





Summary – modeling of hydraulic stimulation

- A numerical approach for simulation of shear stimulation of a complex fracture network in a 3d domain
 - DFM model; fluid flow in both fractures and matrix
- Factors that influence seismicity are studied
 - leakage into the rock matrix reduce seismicity
 - fracture closure is identified as a mechanism for postinjection seismicity

Main references

Ucar, B, Keilegavlen, *Geophys Res Lett*, 2017

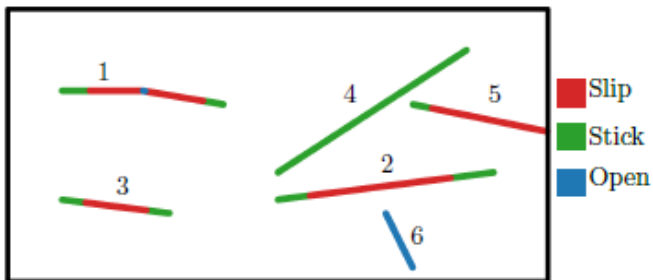
Ucar, B, Keilegavlen, *J Geophys Res Solid Earth*, 2018



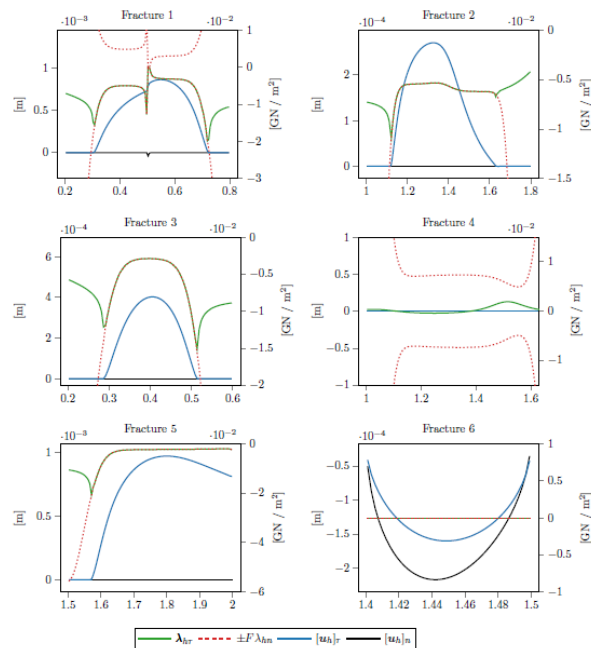
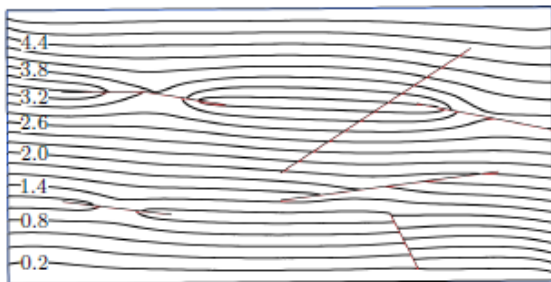
Recent improvements in modeling friction and contact mechanics



Shear test results



x-component of displacement

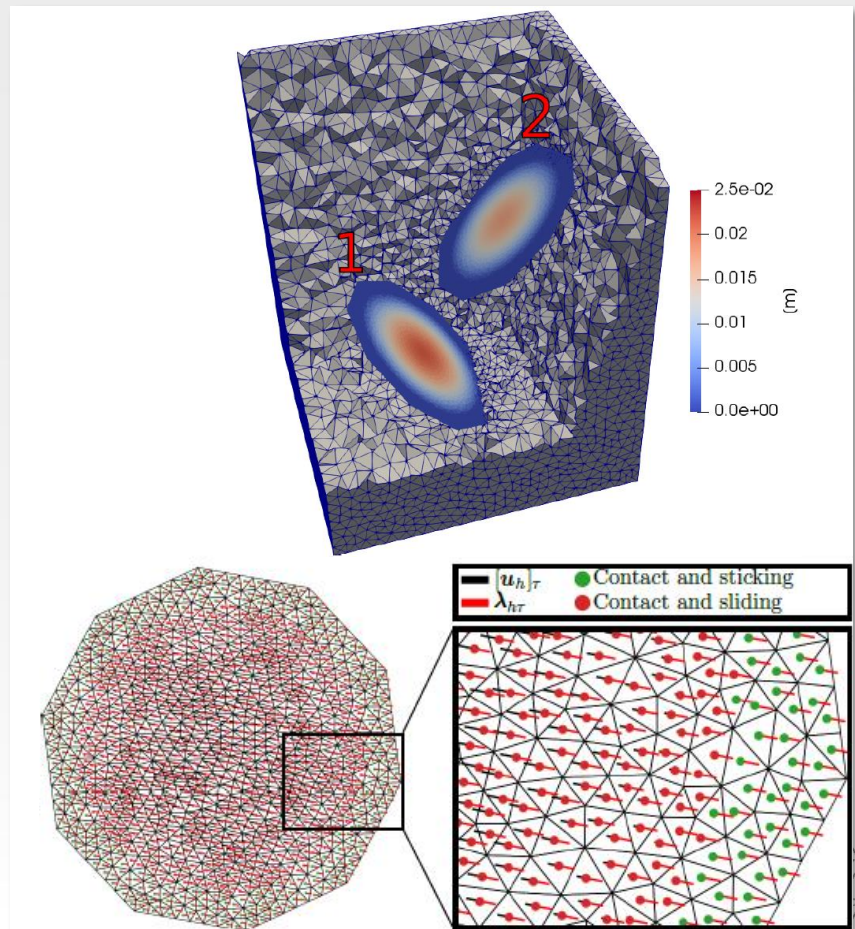
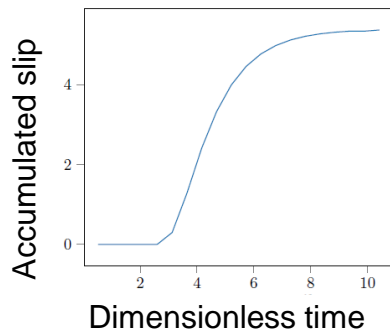


3D and poroelastic effects

3-D example

- bottom boundary: fixed,
- vertical boundaries: rolling,
- top boundary: Neumann load

Including fully coupled poroelasticity

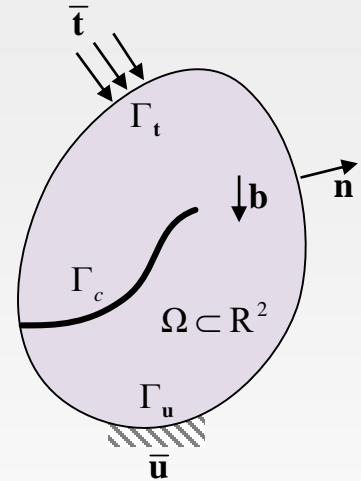




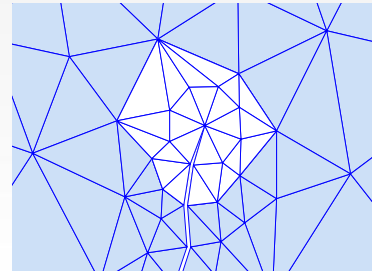
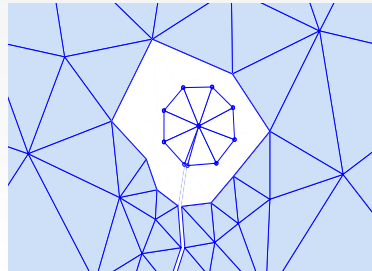
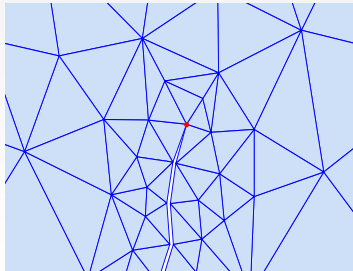
Ongoing work: mixed-mechanism stimulation



$$\left\{ \begin{array}{ll} \nabla \cdot \boldsymbol{\sigma} + \mathbf{b} = 0 & \text{in } \Omega \\ \boldsymbol{\sigma} = \mathbf{C} : \boldsymbol{\varepsilon} & \text{in } \Omega \\ \boldsymbol{\varepsilon} = \frac{1}{2} (\nabla \mathbf{u} + \nabla \mathbf{u}^T) & \text{in } \Omega \\ \mathbf{u} = \bar{\mathbf{u}} & \text{on } \Gamma_u \quad \text{Dirichlet BC} \\ \boldsymbol{\sigma} \cdot \mathbf{n} = \bar{\mathbf{t}} & \text{on } \Gamma_t \quad \text{Neumann BC} \\ \mathbf{t} = 0 & \text{on } \Gamma_c \quad \text{Crack condition} \end{array} \right.$$



Crack tip: collapsed quarter point singular elements / Adaptive remeshing



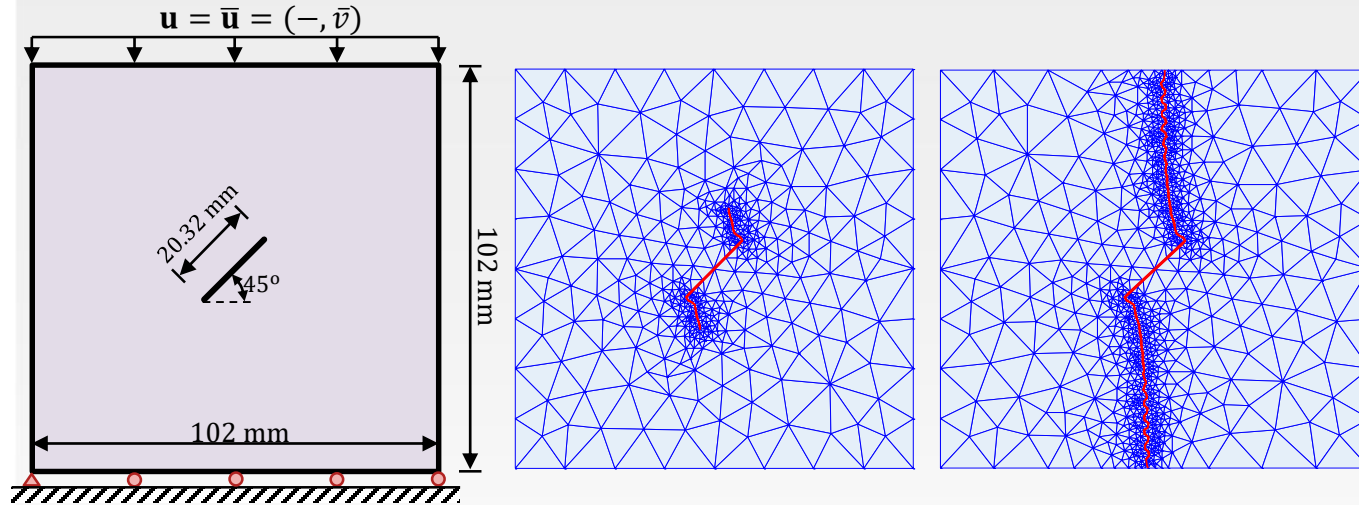
Quarter point elements around crack tip

New mesh

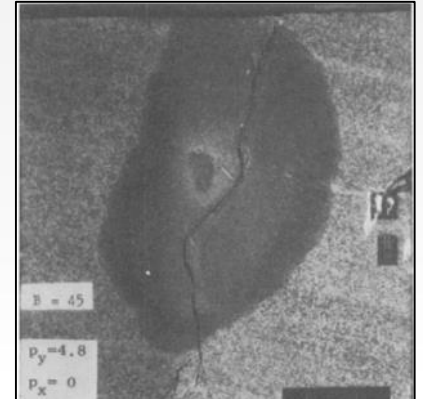




Wing-crack propagation results

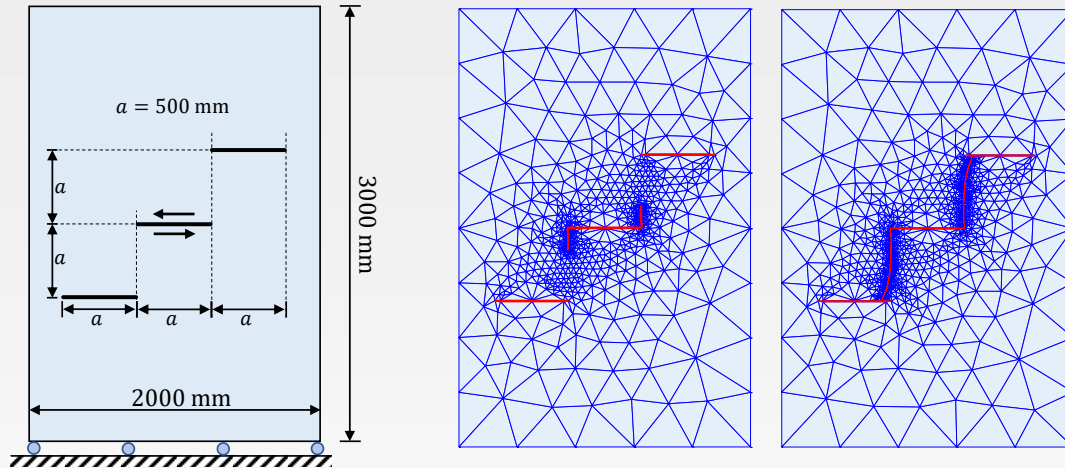


Hau, B and Keilegavlen, submitted European Geothermal Congress, 2019





Wing-crack propagation results



Hau, B and Keilegavlen, submitted European Geothermal Congress, 2019



What's next?

Further model and investigate effects of

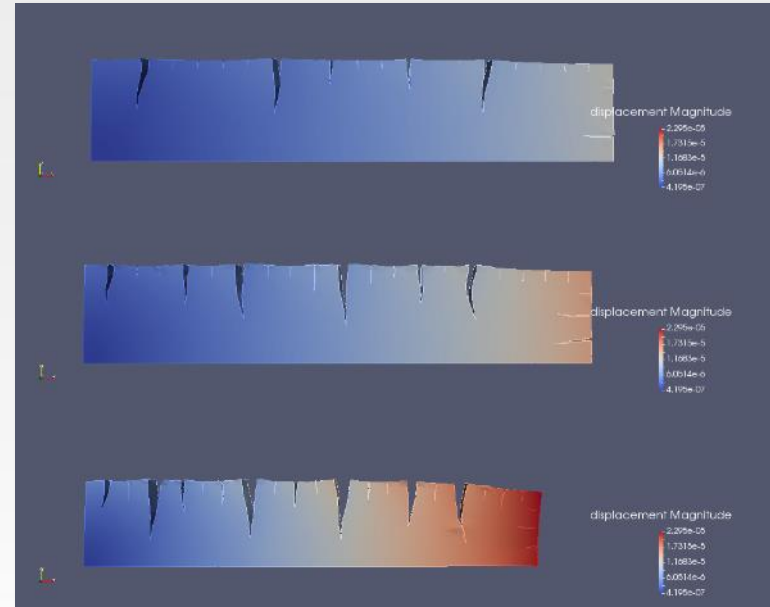
- poroelasticity (Biot)

and then..

- thermoelasticity

Example

- Fractures induced by thermal shock (Fig.)



Stefansson, B, Keilegavlen, Paluszny. Unpublished, 2019



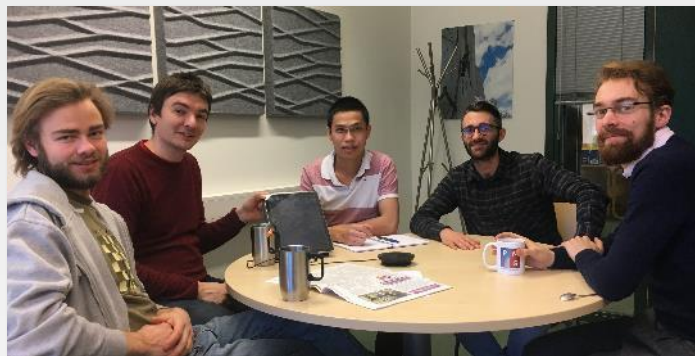


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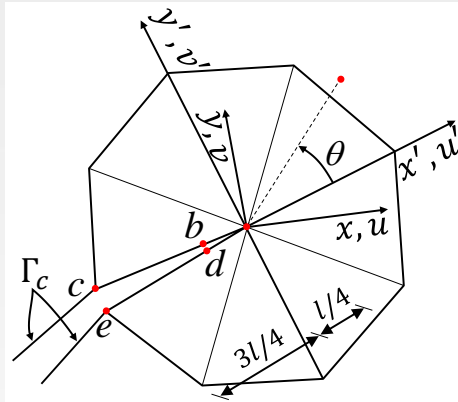
equinor

GeoStim project, Research Council of Norway grant no. 228832
ERIS project, Research Council of Norway grant no. 267908



Open-source code: github.com/pmgbergen/porepy

Fracture criteria



Collapsed quarter point
singular elements - CQPE

1. **Maximum tangential stress: MTS**
2. Minimum strain energy density: MSE
3. Maximum potential energy release rate: ERR
4. Maximum dilatational strain energy density: T-cr
5. Maximum stress triaxiality: M-cr
6. Minimum distance from the crack tip to the core region boundary: R-cr
7. ...

$$f(K_I, K_{II}, \theta) = 0 \quad \text{vs} \quad g(K_I, K_{II}, \theta) > 0$$

$$K_{eq}(\theta, K_I, K_{II}, l) \geq K_{IC}$$

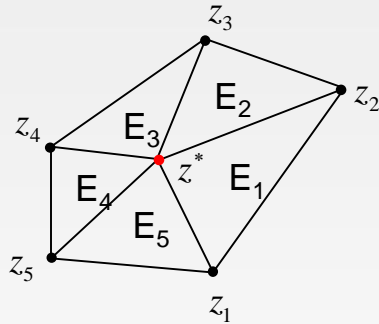
K_I, K_{II} are the stress intensity factors

$$\begin{Bmatrix} K_I \\ K_{II} \end{Bmatrix} = \frac{E}{3(1+\nu)(1+k)} \sqrt{\frac{2\pi}{l}} \frac{1}{2} \begin{Bmatrix} 8(v'_b - v'_d) - (v'_c - v'_e) \\ 8(u'_b - u'_d) - (u'_c - u'_e) \end{Bmatrix}$$

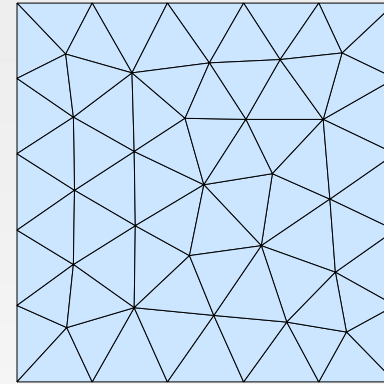
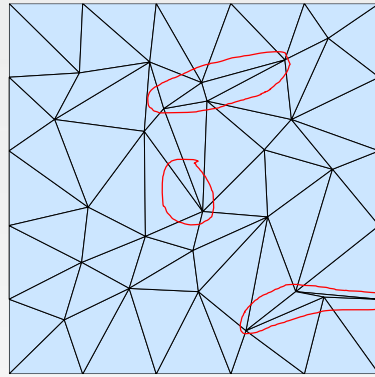
Adaptive Remeshing

Laplacian smoothing

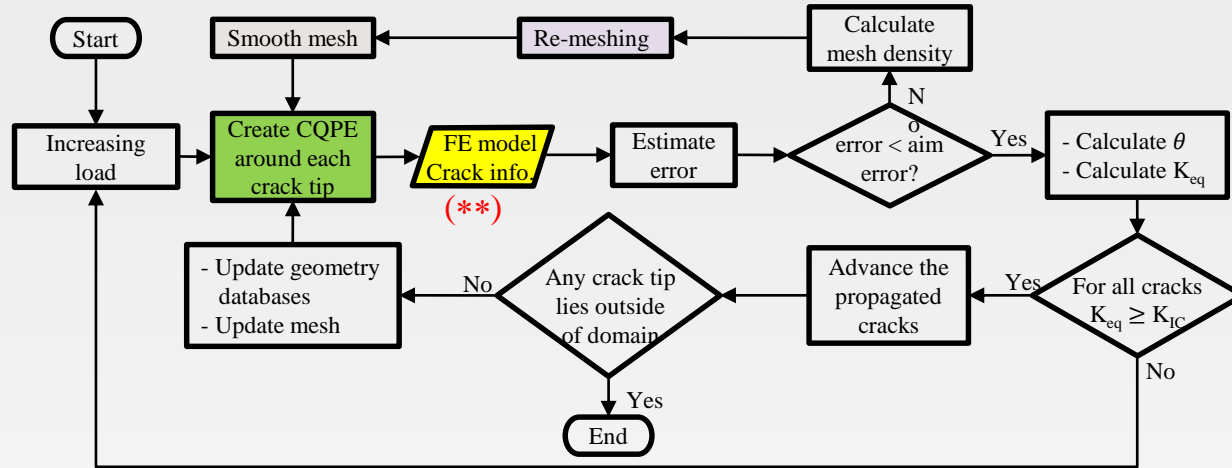
$$z^* = \frac{1}{n} \sum_{i=1}^n z_n$$



Refine vs Remesh
processes



Process sequences of crack propagation simulation



FEM

$$\int_{\Omega} \mathbf{u}^T \mathbf{L}^T \mathbf{D} \mathbf{L} \mathbf{v} d\Omega + \int_{\Omega} \mathbf{b} \mathbf{v} d\Omega + \int_{\Gamma_t} \bar{\mathbf{t}} \mathbf{v} d\Gamma = 0 \quad (*)$$

Discretizing domain Ω into m finite elements that non-overlapping and conform to the crack geometry

$$\Omega \cong \Omega^h \equiv \bigcup_{e=1}^m \Omega_e$$

The displacement field is linearly approximated via displaced values at the three

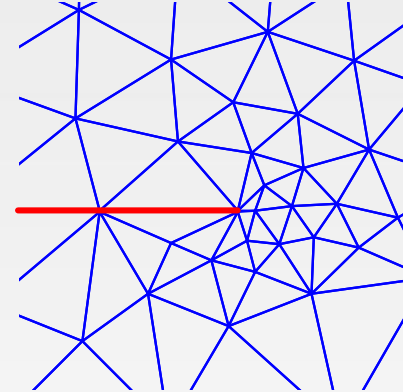
vertices

$$\mathbf{u} = \begin{Bmatrix} u \\ v \end{Bmatrix} \cong \begin{Bmatrix} N_i u_i \\ N_i v_i \end{Bmatrix} = \mathbf{N} \mathbf{u}_h^e$$

The discretized system

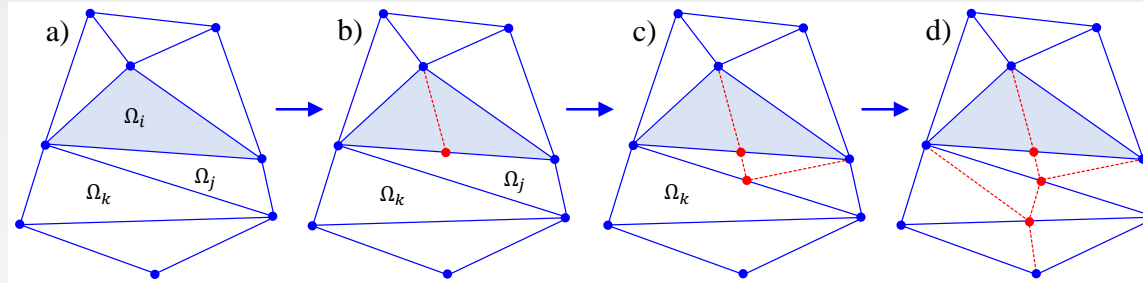
$$\mathbf{K} \mathbf{u}_h = \mathbf{F} \quad (**)$$

Improving the computational efficiency and accuracy of FEM \rightarrow ARM

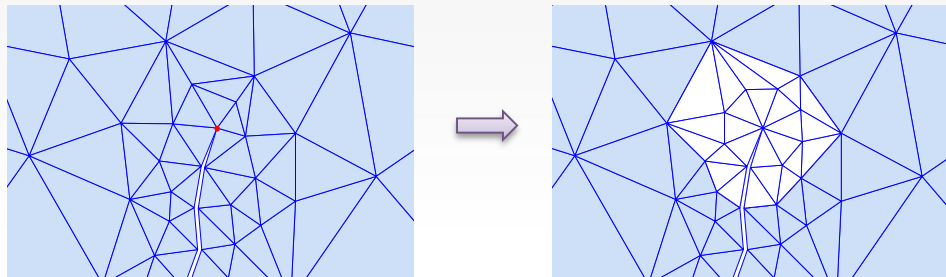


Adaptive Remeshing

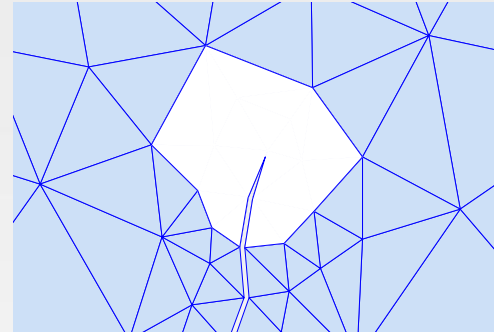
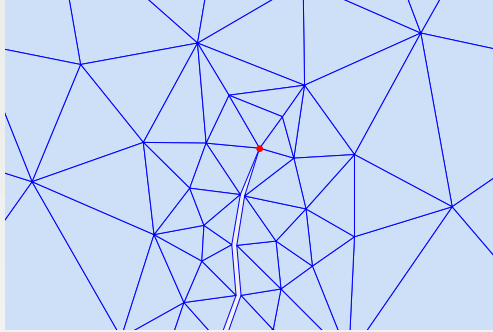
1. Posteriori error \rightarrow Elements need to refine
2. Edge-split operator based on subdivision the longest edge into two new other edges



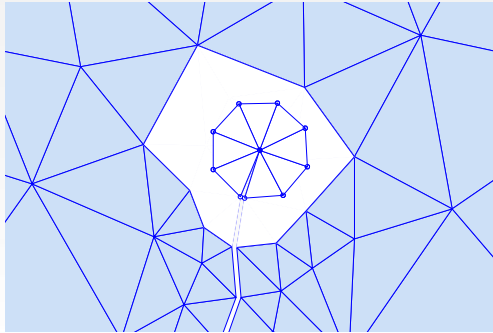
3. Remesh around each crack tip



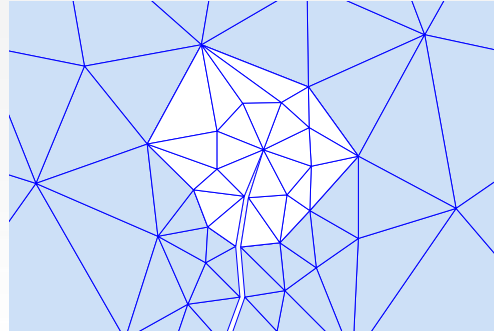
3. Remesh around each crack tip



Delete domain around the tip



Quarter point elements around crack
tip

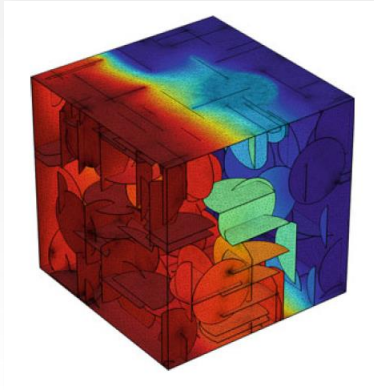


New mesh

Playing the scales - How to upscale to a continuum scale?



- Homogenization
- Effective medium theory
- Numerical upscaling
- Data on upscaled parameters



Sævik, B, Jakobsen & Lien, 2013

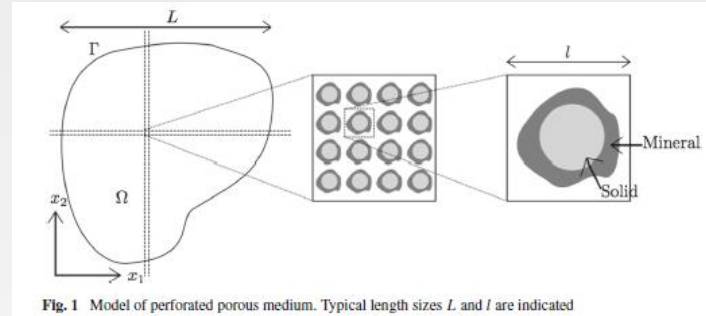
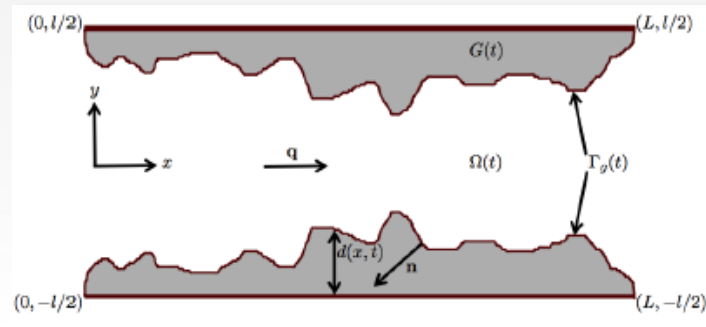


Fig. 1 Model of perforated porous medium. Typical length sizes L and l are indicated

Bringedal, B, Pop & Radu, 2016b

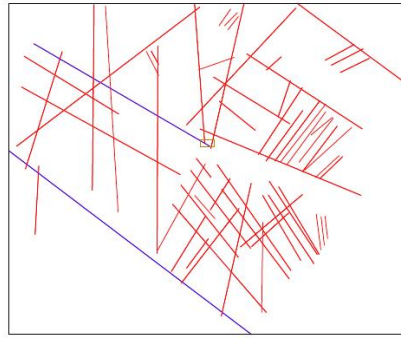


Bringedal, B, Pop & Radu, 2016a

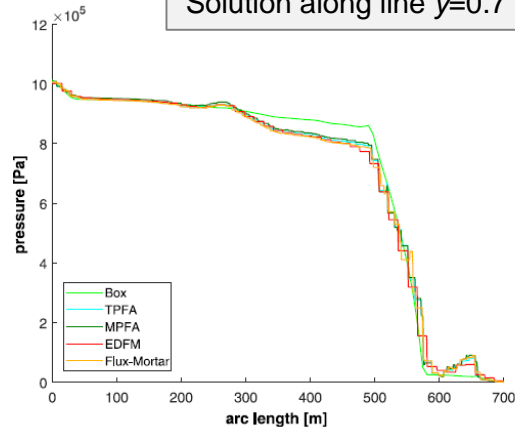




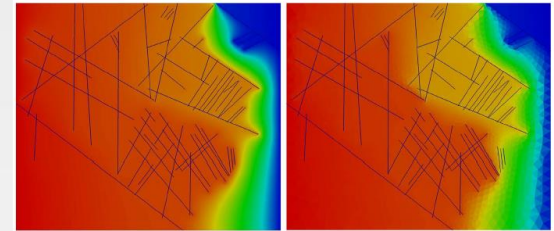
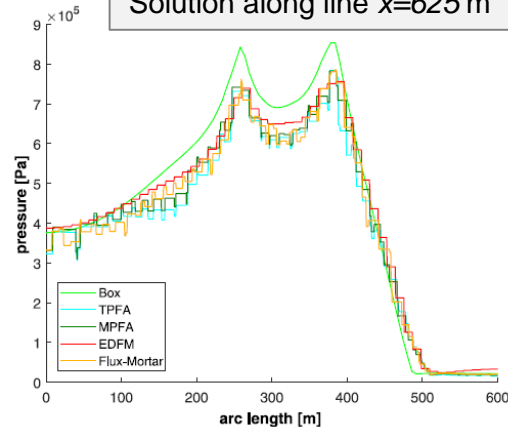
Network based on field data



Solution along line $y=0.7$

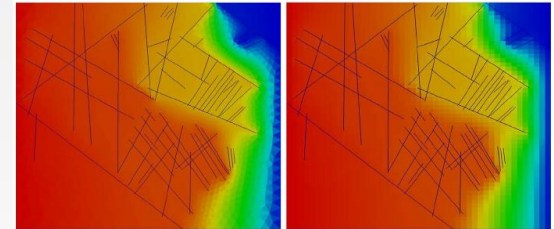


Solution along line $x=625$ m



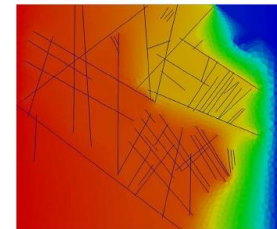
(a) Box

(b) TPFA



(c) MPFA

(d) EDFM



(e) Flux-Mortar



Stress response of matrix due to fracture deformation

Assumptions: quasi-static problem, isotropic medium

- Conservation of Momentum:

$$\nabla \cdot \boldsymbol{\sigma} + \mathbf{f} = 0$$

- Hooke's law

$$\boldsymbol{\sigma} = \mathbf{C} : \boldsymbol{\varepsilon} \quad \text{where } \boldsymbol{\varepsilon} = \frac{(\nabla u + (\nabla u)^T)}{2}$$

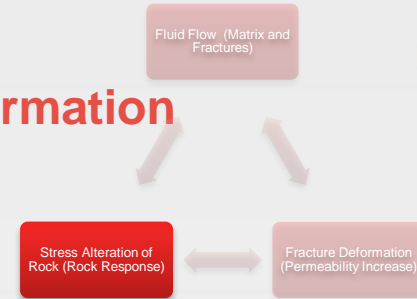
- Fracture deformation vector:

$$\Delta \mathbf{u}_f = (\Delta E_{n,irrev} + \Delta E_{n,rev}) \mathbf{n}_+ + \Delta d_s \boldsymbol{\tau}_+$$

- Fracture deformations conditions on internal boundaries

Numerical Approach

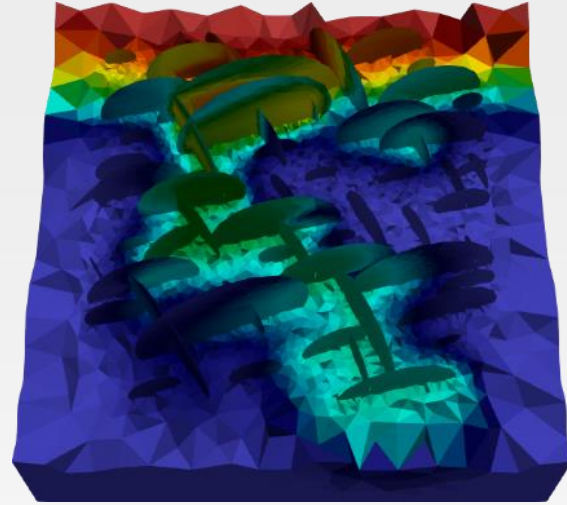
Cell-centered finite-volume method (MPFA) for fractured media





PorePy

github.com/pmgbergen/porepy



Keilegavlen, Fumagalli, Berge, Stefansson, B. "PorePy: An Open-Source Simulation Tool for Flow and Transport in Deformable Fractured Rocks", arXiv, 2017



Mathematical
modeling

Simulation

